

# cMaxDriver: A Centrality Maximization Intersection Approach for Prediction of Cancer-Causing Genes in the Transcriptional Regulatory Network

**Sajedeh Lashgari**

Department of Data Science,  
School of Mathematical  
Sciences, Tarbiat Modares  
University (TMU), Tehran, Iran  
lashgarisajedeh@gmail.com

**Babak Teimourpour \***

Department of Information  
Technology Engineering, School  
of Systems and Industrial  
Engineering, Tarbiat Modares  
University (TMU), Tehran, Iran  
b.teimourpour@modares.ac.ir

**Mostafa Akhavan-Safar**

Department of Computer and  
Information Technology  
Engineering, Payame Noor  
University (PNU), Tehran, Iran.  
akhavansaffar@pnu.ac.ir

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**Abstract**—Cancer-causing genes are genes in which mutations cause the onset and spread of cancer. These genes are called driver genes or cancer-causal genes. Several computational methods have been proposed so far to find them. Most of these methods are based on the genome sequencing of cancer tissues. They look for key mutations in genome data to predict cancer genes. This study proposes a new approach called centrality maximization intersection, cMaxDriver, as a network-based tool for predicting cancer-causing genes in the human transcriptional regulatory network. In this approach, we used degree, closeness, and betweenness centralities, without using genome data. We first constructed three cancer transcriptional regulatory networks using gene expression data and regulatory interactions as benchmarks. We then calculated the three mentioned centralities for the genes in the network and considered the nodes with the highest values in each of the centralities as important genes in the network. Finally, we identified the nodes with the highest value between at least two centralities as cancer causal genes. We compared the results with eighteen previous computational and network-based methods. The results show that the proposed approach has improved the efficiency and F-measure, significantly. In addition, the cMaxDriver approach has identified unique cancer driver genes, which other methods cannot identify.

**Keywords:** Cancer-causing genes; Transcriptional regulatory network; Maximization; Centrality; Intersection.

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\* Corresponding Author

## I. INTRODUCTION

### A. The Importance of Cancer-Causing Genes Discovery

Many studies have been done on cancer-causing genes detection. These genes are known as cancer driver genes (CDGs). CDGs are genes in which mutations cause cancer. The basic idea behind these methods, known as computational and statistical methods, is that repeated mutations in specific genes cause cancer. Not all mutations in a gene lead to cancer. As a result, in these methods, the detection and differentiation of cancer-causing mutations from normal mutations are essential for the identification of cancer genes. Existing methods for detecting CDGs rely heavily on genomic and transcriptomic data. Existing methods can be divided into three categories: computational-based, subnetwork-based and network-based. Computational methods using mutation data and transcriptomic data try to calculate the mutation frequency rate in genes. CoMDP [1], ActiveDriver [2], e-Driver [3], Simon [4], Oncodrive-Fm [5], OncodriverCLUST [6], Dendrix [7], iPAC [8] and MutSigCV [9] are among the computational methods. For example, Simon [4] calculates the effect of mutant function on proteins to find cancer-causing genes. OncodriveFM [5] and OncodriveCLUST [6] are approaches that categorize cancer-causing genes by evaluating the effect of cancer genome types on proteins. Dendrix [7], CoMDP [1] use mutation profiles to identify cancer signaling pathways. MutsigCV [9] uses exome sequences to detect heterogeneity in the cancer dataset and then identifies cancer-causing genes based on the frequency of mutations in different cancer. iPAC [8] also uses a combination of gene expression data and mutation data to identify cancer-causing genes. The ActiveDriver [2] uses information about changed post-transcription sites of proteins in mutant cancer genomes to identify cancer-causing genes. The e-Driver [3] method also tries to find the rate of biased mutations in the functional regions of a protein. Another group of methods for identifying cancer genes is known as sub-network methods. These methods are similar to network methods based on mutation data, but have also used part of the network structure. For example NetBox [10], DawnRank [11], MSEA [12], MeMo [13] and DriverNet [14] are among the sub-network methods. For example, DawnRank attempts to find cancer-causing genes using mutation and transcription data along with molecular interaction network information. Similarly, the NetBox [10] method finds cancer-causing genes from both protein-protein interactions and signaling pathways by finding cancer communities. The third category is network-based methods, which do not use mutation data and only use network structure analysis to identify driver genes. For example, iMaxDriver-N and iMaxDriver-W [15] are two network-based approaches that attempt to identify cancer-causing genes by influence maximizing approach. The characteristics of the methods compared to the proposed method in this study are shown in Table 1.

These methods have some limitations and shortcomings as follows:

- Most of these methods have a high rate of false positives in the results, which results in a decrease in precision and the F-measure.
- In addition, these methods rely heavily on mutation data. This data is naturally accompanied by noise and error. In addition, they may not always be available in the desired quality.
- Most of the genes identified by each of these methods overlap with the set of cancer-causing genes in other methods and are abundantly detected as unique cancer-causing genes.
- Some of these methods, such as the iMaxDriver approaches, are very time-consuming.

According to the limitations of existing methods, in this study, we proposed cMaxDriver as a new network-based approach to predicting cancer-causing genes. This approach identifies cancer-causing genes by analyzing the structure of the transcriptional regulatory network, without using mutation data. cMaxDriver uses an independent source of information. Transcriptional regulatory network (TRN) is one of the basic networks for controlling cellular processes. Transcription factors (TF) are key components of the cell and affect other genes, regulating their expression. In the other words, a transcriptional regulatory network shows how each transcription factor regulates the expression of other transcription factors and genes. Many diseases, including cancer, are caused by abnormalities in the function of transcription factors. This shows the importance of analyzing the structure of these networks in biomedical research.

In this study, a network-based approach called cMaxDriver was proposed to find cancer-causing genes. This approach uses degree, closeness, and betweenness centralities in the human transcriptional regulatory network. The results showed that cMaxDriver is able to improve the prediction precision of previous methods. In addition, cMaxDriver detects genes that other previous methods could not detect. Therefore, it can be used as a complementary method to other existing computational tools. The results show the proposed method performs better than many existing computational and network-based approaches.

### B. Theoretical Foundations

Network centrality is a concept that is widely used in social network analysis to find the position and importance of each node in terms of communication with other nodes [16, 17]. Using centralities, noisy data from the network are reduced. In addition, the most important parts of the network are represented using them. There are different types of centralities, each with various definitions. Here, the three centralities of degree, closeness, and betweenness are used, which are defined below.

- Degree centrality: obtained by using the number of adjacent edges of a node through formula (1) [18].
- Closeness centrality: In connected networks, using the inverse calculation, the shortest path distance of each node from other nodes is obtained in the form of the formula (2) [18].

- Betweenness centrality: In connected networks, this centrality for each node is calculated by using the number of the shortest paths that pass through that node, as formula (3) [18].

$$C_D(p_k) = \sum_{i=1}^n a(p_i, p_k) \quad (1)$$

$$C_c(p_k) = \left( \sum_{i=1}^n d(p_i, p_k) \right)^{-1} \quad (2)$$

$$C_B(p_k) = \sum_{s \neq p_k \neq t} \frac{\sigma_{st}(p_k)}{\sigma_{st}} \quad (3)$$

Where:

$p$  represents the node of the network.

$a(p_i, p_k)$  is the value of the entry  $(i, j)$  of the adjacency matrix  $a$ . In other words the  $a(p_i, p_k)=1$  if there is a directed edge from  $p_i$  to  $p_k$  are in the network and  $a(p_i, p_k)=0$  otherwise.

$d(p_i, p_k)$  is the shortest path distance from  $p_i$  to  $p_k$  in the network.

$\sigma_{st}$  is the total number of shortest paths from node  $s$  to node  $t$ .

$\sigma_{st}(p_k)$  is the number of paths that pass through the  $p_k$  node.

TABLE I. THE DETAILS OF COMPUTATIONAL AND NETWORK-BASED METHODS USED FOR COMPARISON.

Method name	Mutation data	Expression data	Network structure	Methodology
MeMo	✓	-	✓	correlation analysis and statistical tests
NetBox	✓	-	✓	sequence mutations and DNA copy number analysis
OncodriveCLUST	✓	-	-	clustering using mutations assessment
MDPFinder	✓	✓	-	Mutual exclusivity of gene modules
OncodriveFM	✓	-	-	The effect of mutation on genes
DriverML	✓	✓	-	machine learning approach
DawnRank	✓	✓	✓	The effect of downstream expression in molecular interaction networks
MeMo	✓	-	✓	gene correlation and statistical tests
Simon	✓	-	-	impact of mutations on proteins
Dendrix	✓	-	-	Classification of mutations by coverage and exclusivity
ActiveDriver	✓	-	-	identifies protein phosphorylation signaling sites
e-Driver	✓	-	-	Protein mutation rates by binomial test
MutsigCV	✓	✓	-	Calculation of mutations frequency
iPAC	✓	✓	-	Statistical methods
DriverNet	✓	-	✓	Effect of mutations on miRNA network
MSEA	✓	-	✓	combination of data associated with the disease development
iMaxDriver-N	-	✓	✓	Influence maximization approach
iMaxDriver-W	-	✓	✓	Influence maximization approach

## II. METHODOLOGY

In this section, the cMaxDriver pipeline is described. It consists of three different steps:

- 1) Network construction
- 2) Cancer gene search algorithm based on the proposed model
- 3) Evaluation of results based on the existing gold standard

### A. The Study Network

A gene is a specific region of a DNA<sup>2</sup> molecule of a specified length. Genes are found in every cell and carry the information needed to produce proteins, and by expressing these genes, different proteins are produced. Control of these processes plays a key role in determining the proteins present in the cell and their amounts [19]. That is a process that involves transcription on an RNA<sup>3</sup> molecule to translation into mRNA<sup>4</sup>, which eventually leads to the production of new proteins. This process has a great effect on the rate of protein production. A transcriptional regulatory network is a type of biological network that comprises transcription factors and different

<sup>2</sup> Deoxyribonucleic Acid

<sup>3</sup> Ribonucleic Acid

<sup>4</sup> Messenger Ribonucleic Acid

genes and their interactions. The analysis of these networks is useful for examining the flow of information in a biological system and identifying different paths [20]. There are two types of modules in this network, gene module, and transcription factor module. In the first type, several genes are all regulated by one transcription factor, and in the second type, there are several transcription factors that all regulate common genes (see Fig. 1).

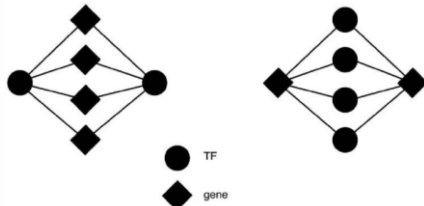


Fig. 1. Types of modules in the gene regulatory network [21].

### B. Network Construction

Gene expression and regulatory interactions are needed to construct the study cancer networks. We used the RegNetwork<sup>5</sup> database [22], which is freely available<sup>6</sup>, to obtain regulatory interactions. In this database, a list of gene regulatory interactions has been collected from various methods and multiple databases. It should be noted that RegNetwork, besides transcriptional interactions, also has regulatory interactions of microRNAs that have been omitted in this study. The retrieved dataset included 150,202 regulatory interactions between gene-TFs and TF-TFs. We also downloaded gene expression of three cancers: Breast (GSE15852), Colon (GSE32323), and Lung (GSE3268) from the GEO<sup>7</sup> database. In this database, gene expression data related to cancerous tissue and its adjacent normal tissue were reported for 10 patients. After initial processing, first, we deleted rows with missing gene names. Some rows had more than one gene name, which was separated. Finally, we computed the average expression values of rows that have the same gene name. Eventually, a file was obtained in which each row belonged to a unique gene and its expression values. Then we constructed separately, the regulatory network for breast, colon, and lung cancer using its gene expression data and regulatory interactions. In this way, for each network, the final list of gene expression values was mapped with the list of regulatory interactions. Thus, if a regulatory interaction of both origin and destination contained gene expression values, it was retained in the network and otherwise removed.

### C. Network Features

The primary regulatory network for three types of cancer was constructed using the approach described in Section 2-2. These networks were disconnected and to analyze them in most cases, it is necessary to be connected. Therefore, we first converted the

networks to connected networks and then performed the necessary analyzes. To do this, we used the largest weakly connected component. For example, in the lung cancer network, we had 11016 nodes, 87388 edges, 2 weakly connected components, and 9997 strongly connected components that the resulting network of lung cancer was constructed using the largest weakly connected component and the number of nodes and edges was 11015 and 87387, respectively. Information about the other two networks is also shown in Table 1. Also, the resulting networks are of directional and connected types. For example, the general view of the lung cancer network is illustrated using the force-directed algorithm in Fig. 2.

To identify and study the network more accurately, we calculated and examined the structural features of the networks. As shown in Fig. 3, the distribution and structure of the networks are more similar to a Scale-Free network.

According to the distribution of the network, it is expected that when a new node is added to the network, it will be connected to nodes with the highest connection and degree. Therefore, these features are investigated using more accurate indicators in the proposed algorithm described in the next section.

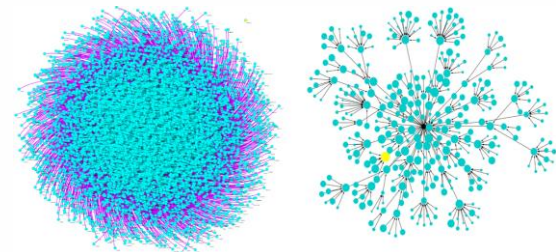


Fig. 2. From left to right: The primary disconnected lung cancer network using the force-directed algorithm, the disconnected component distinguished by its yellow color. Communities from the same network with the Louvain algorithm to better understand the schema and communications, this network has 349 communities, the largest consisting of 814 nodes and distinguished from the rest of the communities in yellow.

TABLE II. STRUCTURE INFORMATION OF THE RESULTING NETWORKS

Network type	Number of		Criterion	Intended network	Random network
	Nodes, Edges	Strongly/Weakly connected components			
Breast cancer	10882, 86380	9870, 2	Average shortest distance	0.298	3.362
			Average clustering coefficient	0.222	$1.459 \times 10^{-3}$
Colon cancer	15664, 117897	14517, 2	Average shortest distance	0.240	3.562
			Average clustering coefficient	0.214	$9.610 \times 10^{-4}$
Lung cancer	11015, 87387	9997, 2	Average shortest distance	0.297	3.367
			Average clustering coefficient	0.223	$1.440 \times 10^{-3}$

<sup>5</sup> Regulatory Network Repository

<sup>6</sup> <http://www.regnetworkweb.org/>

<sup>7</sup> Gene Expression Omnibus

(<https://www.ncbi.nlm.nih.gov/geo/>)



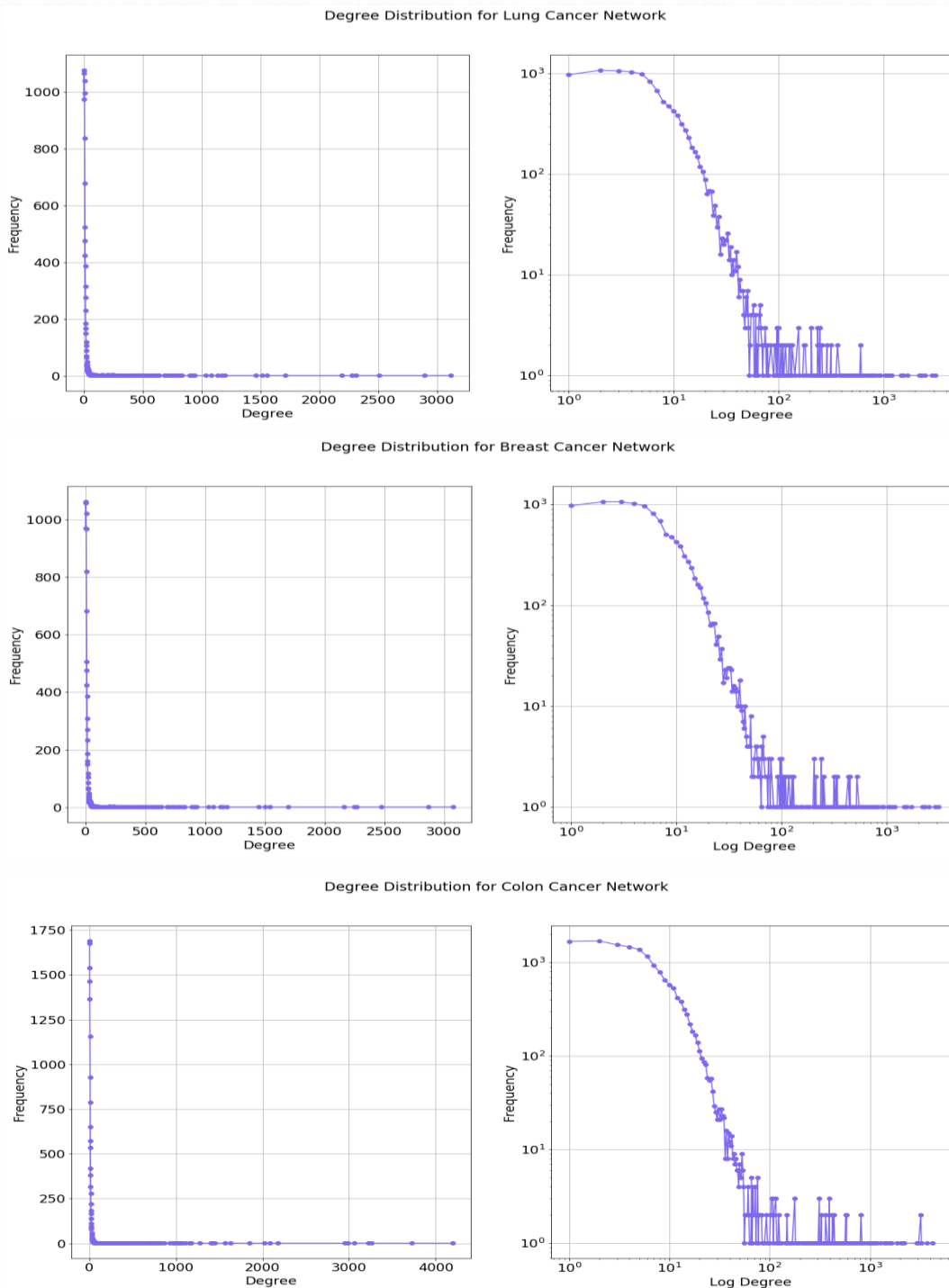


Fig. 3. From left to right: Degree distribution plot and distribution of network degrees in Log-Log scale (by ignoring the first and last nodes, a linear function is observed).

### III. cMAXDRIVER: CENTRALITY MAXIMIZATION INTERSECTION PROPOSED APPROACH

As mentioned earlier, cancer occurs because of abnormalities in some genes and their spread to other genes in the cell regulatory network. Thus, more important genes in network structure are more likely to be classified as driver genes. We proposed a new approach called centrality maximization intersection to predict cancer-causing genes. This algorithm tries to find a subset of nodes that are shared between at

least two centralities. These sets of nodes are communities of genes that satisfy at least the following two conditions and indicate that they are more important in the network. This means that if a mutation occurs in them, it will affect a larger number of genes. Therefore, we considered these nodes as cancer-causing genes (drivers).

These conditions were defined as follows:

- They are more closely related to other genes. (Because of the greater degree centrality)

- They are shorter in distance from other genes and cost less to travel. (Because of the greater closeness centrality)
- They are on the path to more genes, so they affect a lot of genes. (Because of the greater betweenness centrality)

The proposed cMaxDriver algorithm based on the defined conditions comprises seven steps:

- Step 1- Calculation of degree, closeness, and betweenness centralities for all network genes.
- Step 2- Calculate the average of all three centralities.
- Step 3- Define the threshold value for each centrality according to the average value of each.
- Step 4- Find genes that have a value greater than the threshold, separately at each centrality.
- Step 5- Find and separate the data from step 4 that are common to at least two centralities.

- Step 6- Calculate the union of intersection data obtained in step 5.
- Step 7- Delete duplicate data.

The threshold values required in step 3 of the proposed algorithm for each centrality are obtained as described in Section 3-1.

The selected threshold values and other networks information are shown in Table 3. In the lung cancer network, for example, the MYC gene is known as an important node using the cMaxDriver algorithm, because its value in the two centralities has a value greater than the threshold associated with the relevant centrality. This is important, meaning that if a mutation (meaning a cancer-causing mutation) occurs in it, it will have a major impact on other things. Therefore, this gene is considered a driver gene in lung cancer.

TABLE III. INFORMATION ABOUT NETWORK CENTRALITIES.

Network Type	Criterion	Degree centrality	Closeness centrality	Betweenness centrality
Breast cancer	Minimum value	$9.190 \times 10^{-5}$	0	0
	Average value	0.001	0.030	$1.890 \times 10^{-5}$
	Maximum value	0.283	0.540	0.009
	The node corresponding to the maximum value	MAX	MYC	MYC
	Threshold	$1.019 \times 10^{-3}$	$2.547 \times 10^{-1}$	$8.903 \times 10^{-6}$
Colon cancer	Minimum value	$6.384 \times 10^{-5}$	0	0
	Average value	$9.611 \times 10^{-4}$	0.023	$1.068 \times 10^{-5}$
	Maximum value	0.268	0.529	0.007
	The node corresponding to the maximum value	MAX	SP1	SP1
	Threshold	$1.011 \times 10^{-3}$	0.247	$3.006 \times 10^{-4}$
Lung cancer	Minimum value	$9.079 \times 10^{-5}$	0	0
	Average value	$1.441 \times 10^{-3}$	0.029	$1.858 \times 10^{-5}$
	Maximum value	0.283	0.540	0.009
	The node corresponding to the maximum value	MAX	MYC	MYC
	Threshold	$1.491 \times 10^{-3}$	$1.953 \times 10^{-2}$	$1.458 \times 10^{-5}$

#### A. Threshold tuning

To select the best threshold, two stages were performed, in both of which the criterion for optimization was F-measure. In the first stage, five statistical indicators of minimum, average, median, mode, and maximum are used as threshold values. These five indicators summarize the information of all nodes in one value.

The best criterion among these five indicators for all three networks was the average. The best criterion is the index by which F-measure is maximized compared to the rest.

For example, Fig. 4 shows performance compared to different indices of the three centralities for the breast cancer network.

As shown in Fig. 4, the model is sensitive to the threshold value, and as the threshold changes, the performance of the model changes. Fig. 4 shows that the best index is 62 because it has the highest F-measure.

Considering the three rings that are considered for each of the centralities and each of which has five defined values, index 62 is related to the values of 0.001, 0.030, and  $1.890 \times 10^{-5}$ , which are related to the

average of the three centralities of degree, closeness, betweenness, respectively.

In the second stage, based on the output of the first stage (namely the average of each centrality), a search interval is found experimentally to find the improved values for the threshold. The results of this stage are shown in Fig. 5 for the breast cancer network.

Finally, the values that had the highest F-measure value at this stage are considered as the final threshold values, which are expressed in Table 2 as rounded values to three decimal places.

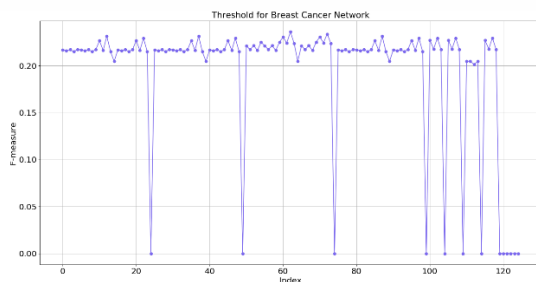


Fig. 4. Model performance at different threshold values in the first stage.

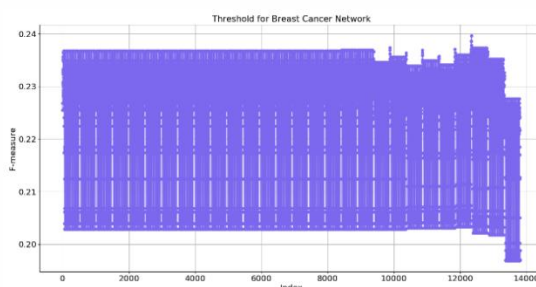


Fig. 5. Model performance at different threshold values in the second stage.

#### IV. EVALUATION OF THE PROPOSED ALGORITHM

As described in Section 3, the algorithm in step 7 considers common unique nodes as cancer-causing genes. The algorithm can finally extract the list of genes as drivers based on the described approach. Then labeling is done for the actual and predicted data. So that the data that truly cause cancer and output data of step 7 of the algorithm, that means predicted driver, are labeled with 1 (negative: driver), and the rest of the data with 0 (positive: normal). We compared the results of the algorithm with eighteen

previous computational and network-based methods. To obtain the results of the previous methods, we used the DriverDBv2 database [23]. In this database, the results of each cancer are reported based on the TCGA<sup>8</sup> dataset for each method. We also used a set of validated cancer-causing genes introduced by TCGA [24] to evaluate the results. TCGA is an evaluation database used in many bioinformatics studies such as [15, 20, and 21]. In this database, datasets are available<sup>9</sup> for three breast, colon, and lung cancers named TCGA-BRCA<sup>10</sup>, TCGA-COAD<sup>11</sup>, and TCGA-LUSC<sup>12</sup>, respectively. That the number of genes as drivers introduced, the same order is 572, 572, and 566 for three different types of cancers.

To evaluate cMaxDriver, we used the criteria of precision, recall, accuracy, and F-measure that are common in binary classification approaches. The F-measure is a common and good criterion for evaluating classifiers, which obtained the percentage of correct positive predictions by calculating the harmonic mean of the two criteria of precision and recall, which is defined as follows:

$$F - \text{measure} = \frac{2 \times \text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}} \quad (4)$$

While precision and recall are defined as follows:

$$\text{Precision} = \frac{TP}{TP + FP} \quad (5)$$

$$\text{Recall} = \frac{TP}{TP + FN} \quad (6)$$

Accuracy is also calculated by Equation (7).

$$\text{Accuracy} = \frac{TP + TN}{TP + TN + FP + FN} \quad (7)$$

Details of the evaluation of the methods used are shown in Tables 3 and 4. For example, in breast cancer, cMaxDriver had 10249 true positives (TP) and 164 true negatives (TN), i.e. it correctly identified 164 genes as a driver and 10249 genes as

<sup>8</sup> The Cancer Genome Atlas

<sup>9</sup> <https://cancer.sanger.ac.uk/census>

<sup>10</sup> Breast invasive carcinoma

<sup>11</sup> Colon adenocarcinoma

<sup>12</sup> Lung squamous cell carcinoma

normal in breast cancer. It also has 408 false positives (FP) and 633 false negatives (FN), which are related to type I and type II errors, respectively. Which shows the number of normal genes that are incorrectly predicted as drivers by this algorithm, and the number of driver genes that are incorrectly predicted as normal by this algorithm, respectively. The complete results are shown in Table 3.

Considering the condition of at least two intersections will give better results than the intersection between all three centralities because the intersection between all three centralities imposes more restrictions on the data, so the results have less bias but more variance. Therefore, as shown in step 5, the proposed method uses the condition of at least two intersections. The results of running the cMaxDriver algorithm on three cancer networks are shown in Table 4. Comparing the results of cMaxDriver with other methods is given in Section 5.

TABLE IV. THE CONFUSION MATRIXES OF CMAXDRIVER

Network Type	Criterion			
	TP	TN	FP	FN
Breast cancer	10249	164	408	633
Colon cancer	15074	158	414	590
Lung cancer	10449	153	413	566

TABLE V. VALUES OBTAINED FROM CMAXDRIVER EVALUATION.

Network Type	Criterion			
	Accuracy	Precision	Recall	F-measure
Breast cancer	0.909	0.206	0.287	0.240
Colon cancer	0.938	0.211	0.276	0.239
Lung cancer	0.915	0.213	0.270	0.238

## V. RESULTS

The proposed algorithm was run on three cancer networks. Then, based on the threshold values introduced in Section 3, the genes were classified into two classes: driver and normal. Afterward, using the performance criteria introduced in Section 4, we compared cMaxDriver with eighteen

previous computational and network-based methods. The corresponding results for breast cancer are shown in Fig. 6. As seen, cMaxDriver with Recall = 0.287 is ranked first among network-based methods and ranked second among all computational and network-based methods. Although some computational methods have higher precision and recall they are not in a good position in terms of the F-measure and the number of cancer-casual genes they predict.

As mentioned, precision and recall alone cannot show the performance of a classification system. Therefore, the harmonic mean of these two criteria is used. As shown in the results, cMaxDriver with F-measure = 0.24 has the highest value among all computational and network-based methods and has significantly improved performance.

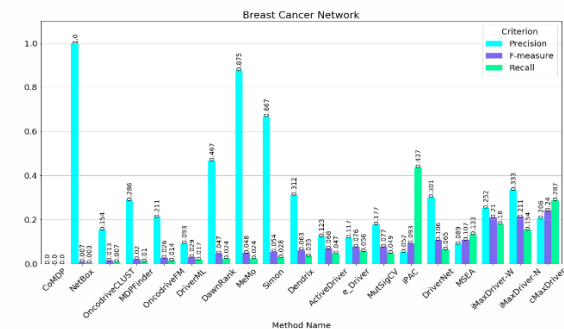


Fig. 6. Comparison of evaluation criteria of the cMaxDriver and other methods in breast cancer.

We also compared the cMaxDriver and other methods based on the number of driver genes predicted. The results are shown in Fig. 9. As seen, cMaxDriver reached ranks first among previous network-based methods and second among all methods by identifying 164 genes in breast cancer.

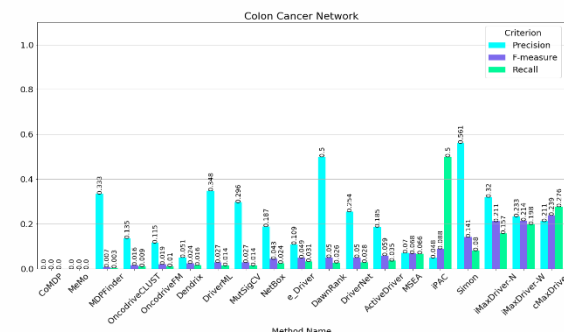


Fig. 7. Comparison of evaluation criteria of the cMaxDriver and other methods in colon cancer.

The results of cMaxDriver and other methods in colon cancer are shown in Fig. 7. As seen, cMaxDriver with F-measure =



0.239 has the highest value among all computational and network-based methods and has significantly improved performance. Also, in terms of the number of drivers detected, as shown in Fig. 9, cMaxDriver, with 158 drivers detected for colon cancer, ranks first among previous network-based methods and second among all methods.

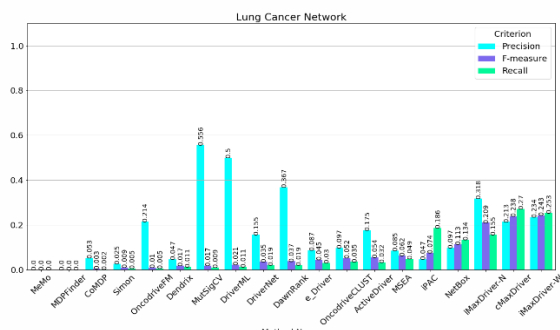


Fig. 8. Comparison of evaluation criteria of the cMaxDriver and other methods in lung cancer.

Also, based on Fig. 8 be seen, cMaxDriver for lung cancer by F-measure = 0.238 with a slight difference after iMaxDriver-W among all computational and network-based methods is ranked second, but based on Recall = 0.27, it's ranked first among all methods. In addition, based on the number of drivers detected, as seen in results are shown in Fig. 9, cMaxDriver reached ranked first among all computational and network-based methods by identifying 153 genes in lung cancer.

We also compared the overlap of genes identified by cMaxDriver and other methods. The results are shown as a Venn diagram in Fig. 10. As seen in Fig. 10, cMaxDriver was able to cover 140, 143, and 135 genes identified by other computational and network-based methods in breast, Colon, and lung cancer, respectively. In addition, it has identified 24, 15, and 18 unique genes in breast, colon, and lung cancer that have not been identified by any of the previous computational and network-based methods.

Also, compared to previous network-based methods, cMaxDriver identified 123, 123, and 129 cancer-causing genes detected by other network-based methods in the same order. In addition, cMaxDriver similarly identified 41, 35, and 24 unique genes in the three named cancers that were not detected by other network methods. Lists of unique cancer-causing genes correctly identified by cMaxDriver is given in Tables 5.

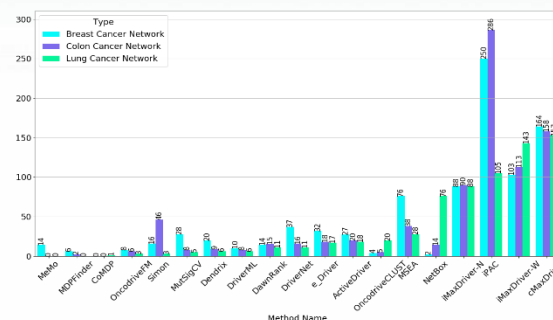


Fig. 9. Comparison of the number of cancer-causing genes identified by cMaxDriver and other methods in three types of cancer.

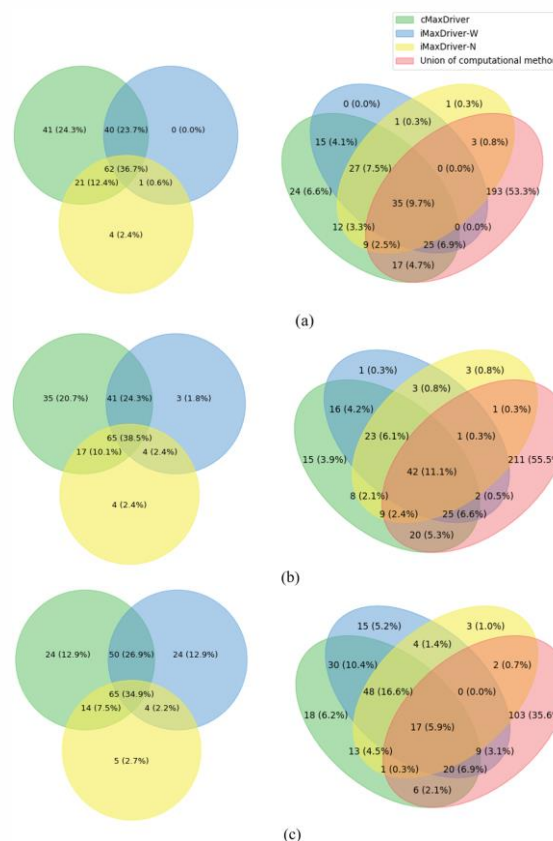


Fig. 10. Left to right: Overlap of genes identified by cMaxDriver with other network-based methods and with other methods. (a), (b), and (c) are related to breast, colon, and lung cancers, respectively.

The main aim of the study was not to examine time complexity. The primary objective was to improve the performance criteria and the number of identified driver genes. In addition the time complexity of the previous methods is not mentioned. However, program run time of our proposed method (step 1 to 7) in a system with CPU intel core i5 and Ram 8 are as follows: breast cancer=62ms, colon cancer= 61ms and lung cancer =75ms. These values do not include the time to set the optimal threshold.

## VI. CONCLUSION

In this study, an algorithm called cMaxDriver was proposed to classification and detection cancer-causing genes in transcriptional regulatory networks. One of the advantages of proposed method is that it does not depend on mutation and genomic data. And

identifies driver genes only using the structure of gene interactions and the network approach. It is also much faster than previous networking methods. The cMaxDriver has the best performance compared to other computational and network-based methods in terms of f-measure and the number of diagnostic drivers. First, three cancer regulatory networks were constructed using gene expression and regulatory interactions data. Then the different steps of the algorithm were performed on the networks, as described in Section 3. Finally, genes were classified into cancer-casual and normal based on defined threshold values. The results were compared with eighteen computational and network-based methods in terms of efficiency criteria and the number of identified cancer-casual genes. The results in terms of efficiency and F-measure ranked first among all

methods of detecting breast and colon cancer and second in terms of identifying the number of cancer-casual genes. Also, for lung cancer, the proposed algorithm ranks first among all computational and network-based methods in terms of the number of cancer-causing genes detected and second in terms of performance with a slight difference from the first rank. In addition, the proposed approach, while identifying a significant number of diagnostic genes by other methods, can identify genes that have not been identified by any of the other methods.

#### Data availability:

Data is available publicly at  
<https://github.com/MASafar/cMaxDriver>.

TABLE VI. THE LIST OF UNIQUE CANCER-CAUSING GENES PRODUCED BY cMAXDRIVER.

Breast Cancer Network		Colon Cancer Network		Lung Cancer Network	
Compared to all methods	Compared to network-based methods	Compared to all methods	Compared to network-based methods	Compared to all methods	Compared to network-based methods
SMARCB1 MLLT1 ETV6 TAL1 ERCC2 FUBP1 SMARCE1 MDM4 OLIG2 ETV1 TNFAIP3 SMARCD1 KAT6A MAFB BTG1 ELL ETV5 DEK LMO1 MLLT3 DDB2 NR4A3 ELF4 BCOR	NONO SMARCB1 MLLT1 CHD4 ETV6 TAL1 ERCC2 FUBP1 SMARCE1 PSIP1 ZMYM2 MDM4 OLIG2 ETV1 TNFAIP3 HOXD13 AFF1 ERCC3 PBRM1 KAT6A SMARCD1 MLLT10 MAFB BTG1 FUS PRRX1 NSD1 ELL ETV5 XPC CIC DEK ATRX LMO1 MLLT3 DDB2 KAT6B MED12 NR4A3 ELF4 BCOR	DDB2 IKZF1 SMARCE1 BTG1 BCL11B TRIM33 KDM5A HMGA2 XPC POU2AF1 NR4A3 HOXA13 ETV5 SRSF3 SMARCD1	SMARCB1 CHD4 FOXP1 APC SMARCE1 BCL11B HOXC13 ETV1 PAX3 ZFHX3 HOXD13 ERCC3 ARID1B SMARCD1 IKZF1 BTG1 TRIM33 HMGA2 PRRX1 POU2AF1 NSD1 ELL HOXA13 ETV5 XPC SRSF3 NFIB CIC DEK ATRX MLLT3 DDB2 KAT6B KDM5A NR4A3	LMO1 MLLT3 MLLT10 BCL11B HOXC13 TRIM33 ETV6 MLLT1 CIC DEK ELL AFF1 ERCC3 ETV5 XPC NFIB TFE3 SMARCD1	ETV6 MLLT1 BCL11B HOXC13 ETV1 PAX3 TNFAIP3 AFF1 ERCC3 SMARCD1 MLLT10 TRIM33 NSD1 ELL ETV5 XPC NFIB CIC TFE3 DEK ATRX LMO1 MLLT3 MED12

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**Sajedeh Lashgari** is a M.Sc. student in Data Science at Tarbiat Modares University and she received her B.Sc. degree in Statistics from Imam Khomeini International University. Her research interests include Data Mining, Deep Learning, Graph Learning, and Social Network Analysis. And her favorite fields in scientific study include Neuroscience, Clean Energy, Strategy, and Genetics.



**Babak Teimourpour** obtained his Ph.D. in Industrial Engineering from Department of Industrial Engineering, Tarbiat Modares University (TMU), Tehran, Iran. He teaches Ph.D. and M.Sc. level courses. His research interests include Data Mining and Social Network Analysis. His team won the Iran Data Mining Cup in 2010.



**Mostafa Akhavan-Safar** is an Assistant Professor of Information Technology Engineering currently at the School of Computer and Information Technology Engineering of Payame Noor University (PNU). He received his M.Sc. in Information Technology Engineering from Iran University of Science and Technology (IUST), and

Ph.D. in Information Technology Engineering from Tarbiat Modares University (TMU), Tehran, Iran. His research interests include Bioinformatics, Data Mining, Machine learning, Information systems and Social Network Analysis.